

# Towards an adaptive vertical coordinate in MOM6

Angus Gibson

7 May 2018

# Background

- ▶ Hybrid coordinates are currently in use in MOM6 (HyCOM-like)
- ▶ Require a prescriptive and sensitive configuration:
  - ▶ Expected densities and a nominal depth for all layers
  - ▶ Depths chosen conservatively to avoid problems with surface boundary layer
- ▶ Biggest shortcomings: overflows and exchanges

# Regridding/remapping

- ▶ Specify an arbitrary grid  $z_k(x, y)$  for the entire domain with a *regridding function*
- ▶ Given the previous grid  $z_k^n(x, y)$  and the model state (T, S, ...), generate a new grid  $z_k^{n+1}$
- ▶ State is conservatively *remapped* from the source grid to the destination grid
- ▶ Very generalised operation
  - ▶ This does not even require that the grids have the same number of levels!

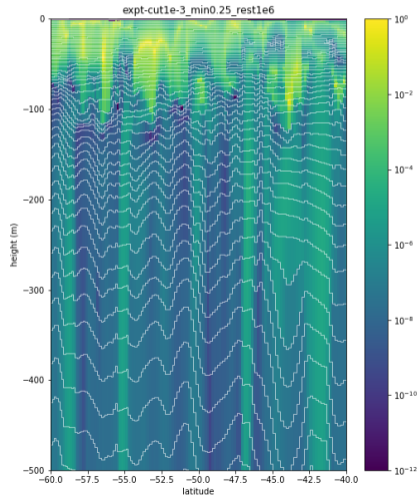
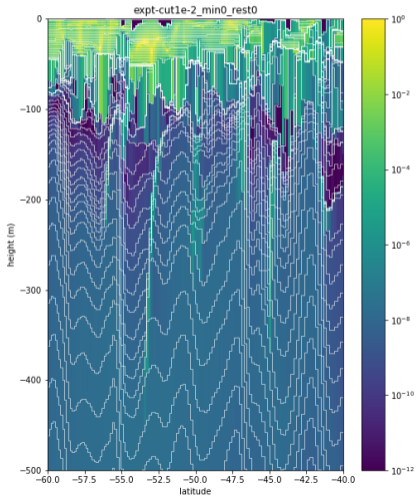
# Equation

- ▶ We want to represent our grid by a single equation that can be understood mathematically and intuitively

$$\partial_t z_k = -\vec{\nabla} \cdot \left( \omega_\sigma \frac{\kappa \nabla \sigma}{\sigma_z} + \omega_z \kappa \nabla z_k \right) + \tau^{-1} (\langle z_k \rangle - z_k) + ???$$

# Examples

- ▶ Iterate regridding/remapping on a z-space snapshot



# Density adaptivity

$$\partial_t z_k = -\vec{\nabla} \cdot \left( \omega_\sigma \frac{\kappa \nabla \sigma}{\sigma_z} + \omega_z \kappa \nabla z_k \right) + \tau^{-1} (\langle z_k \rangle - z_k)$$

- ▶ Using a stencil surrounding the current gridpoint (i.e. the grid communicates laterally)
- ▶ Conserves mean layer height (what goes up in one cell must come down in another)
- ▶ Strongly limited (think of a see-saw on a hill)

# Horizontal smoothing

$$\partial_t z_k = -\vec{\nabla} \cdot \left( \omega_\sigma \frac{\kappa \nabla \sigma}{\sigma_z} + \omega_z \kappa \nabla z_k \right) + \tau^{-1} (\langle z_k \rangle - z_k)$$

- ▶ *Smooth* layers horizontally (not always flat!) and conservatively
- ▶ Split into strongly limited and weakly limited contributions
  - ▶ If  $\omega_z$  is constant, only limited by top and bottom surfaces
- ▶ Use an isopycnal slope to decide regions of smoothing or adaptivity
  - ▶  $\omega_\sigma$  vs.  $\omega_k$

# Restoring

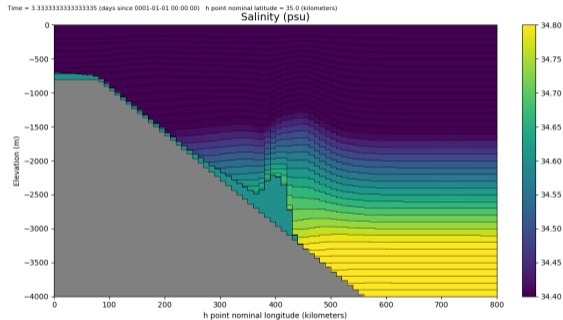
$$\partial_t z_k = -\vec{\nabla} \cdot \left( \omega_\sigma \frac{\kappa \nabla \sigma}{\sigma_z} + \omega_z \kappa \nabla z_k \right) + \tau^{-1} (\langle z_k \rangle - z_k)$$

- ▶ Source term – doesn't have to conserve mean layer height
- ▶ Tried to design this in such a way to ensure resolution doesn't drift from where it was initially
- ▶ Turns out this is approximately equivalent to computing APE – much too expensive
- ▶ Would more realistically be used to gently restore toward a target grid, but maintain adaptivity perturbations



# Another adjustment term?

- ▶ The previous terms miss one key process:
  - ▶ Layers with different k-index (i.e. not laterally connected) but the same density
- ▶ e.g. flow downslope – how do we know which layer we should be in?



# What's next

- ▶ Models are Murphy's Law machines: the overflow problem will show up at some point
- ▶ We can test the coordinate in an idealised configuration and/or 1° global